

General relativity. Problem set 5.

HS 14

Due: Tue, October 21, 2014

1. Torsion and Hessian

The Hessian of a (smooth) function $f: \mathbb{R}^n \rightarrow \mathbb{R}$ is the matrix $\partial^2 f = (f_{,ij})_{i,j=1}^n$ of its second derivatives $f_{,ij} = f_{,ij}(x)$. It is evidently symmetric.

For a function on a manifold M , the gradient covector df has the first derivatives $(f_{,i})_{i=1}^n$ as its components with respect to a coordinate basis; however the second derivatives do not transform as tensor components.

Given an affine connection ∇ , the gradient is $df = \nabla f$ (why?) and a substitute Hessian may be defined as

$$H = \nabla^2 f \equiv \nabla \nabla f.$$

It is a tensor field of type $\binom{0}{2}$. Show: It is symmetric, $H(X, Y) = H(Y, X)$ for all $f \in \mathcal{F}$, iff the torsion vanishes.

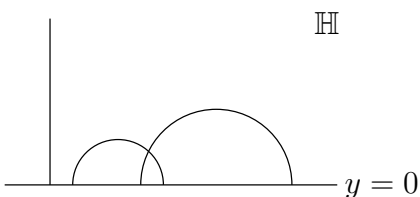
2. Euclidean metric in polar coordinates

Consider the Euclidean plane as a Riemannian manifold $M = \mathbb{R}^2 \ni (x^1, x^2) = x$ with metric $g = dx^1 \otimes dx^1 + dx^2 \otimes dx^2$. Compute the metric in polar coordinates r, φ and the Christoffel symbols (3.6) of the Levi-Civita connection. Verify that they agree with those computed in Problem 3.1.

3. Geodesics in the hyperbolic plane

Consider the hyperbolic plane: $\mathbb{H} = \{(x, y) \in \mathbb{R}^2 | y > 0\}$ with the metric $g = y^{-2}(dx \otimes dx + dy \otimes dy)$.

- Write the geodesic equation.
- Find the quantities which are conserved along the geodesics.
- Show that the geodesics are the Euclidean half-circles (including half-lines), centered on the line $y = 0$.



Hint: Show that the (extrinsic) curvature

$$\rho = \frac{\dot{x}\ddot{y} - \dot{y}\ddot{x}}{(\dot{x}^2 + \dot{y}^2)^{3/2}}$$

is constant along geodesics.

4. An affine connection on Lie groups

Consider a Lie group G (see Problem 3.2).

a) Show that there is a unique affine connection ∇ on G with the properties that

- i) for any left-invariant vector field V on G , the tangent vectors $d\gamma/dt = V_{\gamma(t)}$ to any of its orbits $\gamma(t)$ are parallel transported along it;
- ii) the torsion vanishes.

To define a connection ∇ is tantamount to prescribing its coefficients $\langle e^\alpha, \nabla_{e_\beta} e_\gamma \rangle$, see (2.12), w.r.t. vectors e_α , resp. covectors e^β forming dual bases (e_1, \dots, e_n) , (e^1, \dots, e^n) . These fields are not necessarily coordinate bases, see (2.17, 2.18).

b) Show that the connection of part (a) has coefficients

$$\langle e^\gamma, \nabla_{e_\alpha} e_\beta \rangle = \frac{1}{2} C^\gamma_{\alpha\beta}, \quad (1)$$

where the e_α are left-invariant basis fields and $C^\gamma_{\alpha\beta} = -C^\gamma_{\beta\alpha}$ their structure constants (see Problem 3.2 iv).

Hint: What are the equations for ∇ expressing (i, ii)? Rewrite them in terms of a left-invariant basis e_i and obtain two conditions on $\nabla_{e_\alpha} e_\beta$. Finally, take their sum and difference.