In Exercise 1 we saw that the Langevin equation is a powerful tool for the investigation a particle moving in a fluid by using a stochastic function  $\xi(t)$ , a microscopic quantity. However, there is another access to the problem based on macroscopic terminology, the Fokker-Planck equation.

Given a probability distribution  $P(x_0, t_0)$  for the location of a single particle at  $t = t_0$ , the Fokker-Planck equation determines the evolution of P(x, t) for  $t > t_0$ . A simple version of the Fokker-Planck equation is given by

$$\frac{\partial}{\partial t}P(x,t) = -\frac{\partial}{\partial x}\left[A(x,t)P(x,t)\right] + \frac{\partial^2}{\partial x^2}\left[B(x,t)P(x,t)\right]$$
(1)

where A(x, t) is denoted as the drift term and B(x, t) is the diffusion term. In the following, we want to derive it for a simple model.

## Exercise 2.1 Random Walk

We want to derive the Fokker-Planck equation and its solution for a simple model, the socalled random-walk model. This model consists of a particle moving in a (for simplicity) one dimensional lattice  $(x_{i+1} - x_i = a)$  and in discrete time steps  $t_j$   $(t_{j+1} - t_j = \tau)$ . At each time step the particle can hop with equal probability  $p_{\rightarrow} = p_{\leftarrow} = p = 1/2$  either to the left hand or to the right hand side, see Fig. 1.

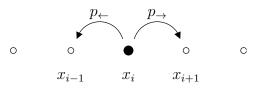


Figure 1: Hopping of a particle from  $x_i$  to  $x_{i-1}$  with probability  $p_{\leftarrow}$  or to  $x_{i+1}$  with  $p_{\rightarrow}$ .

The probability distribution  $P(x_i, t_j; x_0, t_0)$  of the particle satisfies the conditions

$$P(x_i, t_0; x_0, t_0) = \delta_{x_i, x_0}$$
(2)

$$\sum_{x_i} P(x_i, t_j; x_0, t_0) = 1$$
(3)

where Eq. (2) fixes the initial condition at  $t_j = t_0$  and Eq. (3) is due to particle number conservation.

It is not hard to see that the time evolution is given by

$$P(x_{i}, t_{j} + \tau; x_{0}, t_{0}) = P(x_{i-1}, t_{j}; x_{0}, t_{0}) \cdot p_{\rightarrow} + P(x_{i+1}, t_{j}; x_{0}, t_{0}) \cdot p_{\leftarrow}$$
  
$$= \frac{1}{2} (P(x_{i-1}, t_{j}; x_{0}, t_{0}) + P(x_{i+1}, t_{j}; x_{0}, t_{0})).$$
(4)

a) Verify that P fulfills the equation

$$\left[\partial_t^{\tau} - \frac{a^2}{2\tau}\Delta_a\right] P(x_i, t_j; x_0, t_0) = 0$$
(5)

where the operators  $\partial_t^{\tau}$  and  $\Delta_a$  are defined as

$$\partial_t^{\tau} f(x_i, t_j; \dots) = \frac{f(x_i, t_{j+1}; \dots) - f(x_i, t_j; \dots)}{\tau}$$
(6)

$$\Delta_a f(x_i, t_j; \dots) = \frac{1}{a^2} \Big[ f(x_{i+1}, t_j; \dots) + f(x_{i-1}, t_j; \dots) - 2f(x_i, t_j; \dots) \Big].$$
(7)

b) Show that  $P(x_i, t_j; x_0, t_0)$  is given by

$$P(x_i, t_j; x_0, t_0) = \int_{-\pi/a}^{\pi/a} \frac{dk}{2\pi} (\cos ka)^{t_j - t_0/\tau} e^{ik(x_i - x_0)}$$
(8)

by solving Eq. (4).

Hint: Work in Fourier space and use

$$P(x_i, t_j; x_0, t_0) = \int_{-\pi/a}^{\pi/a} \frac{dk}{2\pi} P(k, t_j; x_0, t_0) e^{ikx_i}$$
(9)

where  $P(k, t_0; x_0, t_0)$  is defined by

$$P(k, t_j; x_0, t_0) = \sum_{x_i} P(x_i, t_j; x_0, t_0) e^{-ikx_i}.$$
(10)

c) Calculate the continuum limit  $(a \to 0, \tau \to 0)$  of Eq. (5) and (8) provided that  $a^2/2\tau \equiv D$  is kept constant.

**Hint:** Expand  $\cos x \approx 1 - x^2/2$  and use the identity  $e^x = \lim_{N \to \infty} (1 + x/N)^N$ .

d) Now let's assume that there is an inbalance in the hopping, i.e. we have  $\lambda > 0$  such that

$$p_{\to} = \frac{1}{2}(1+\lambda), \qquad p_{\leftarrow} = \frac{1}{2}(1-\lambda).$$
 (11)

Introduce the parameter  $c = \gamma a/\tau$  and find the corresponding partial differential equation (in the continuum limit) for this case!

Solve the differential equation using the ansatz

$$P_{new}(x,t;x_0,t_0) = P(x-f(t),t;x_0,t_0)$$
(12)

where P is the solution of (c).