## Quantenmechanik I

HS 09
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## Exercise 9.1 Minimum uncertainty wavefunction

Assuming $\langle x\rangle=\langle p\rangle=0$, the uncertainties come

$$
\begin{aligned}
& \delta p=\sqrt{\left(\psi, p^{2} \psi\right)}=\|p \psi\| \\
& \delta x=\sqrt{\left(\psi, x^{2} \psi\right)}=\|x \psi\|
\end{aligned}
$$

The Heisenberg uncertainty relation comes from

$$
\begin{aligned}
|(\psi,[x, p] \psi)| & =|(\psi, x p \psi)-(\psi, p x \psi)| \\
& =|(x \psi, p \psi)-(p \psi, x \psi)| \\
& =\left|(x \psi, p \psi)-(x \psi, p \psi)^{*}\right| \\
& =|2 i \Im(x \psi, p \psi)| \\
& \leq 2|(\psi, x p \psi)| \\
& \leq 2| | x \psi\left|\|\mid\| \psi \| \Rightarrow \frac{\hbar}{2} \leq \delta x \delta p\right.
\end{aligned}
$$

where $\Im$ stands for the imaginary part. To calculate the wave function that minimises $\delta x \delta p$, we need these two inequalities to become equalities.
For the first one,

$$
|2 i \Im(x \psi, p \psi)|=2 \mid(\psi, x p \psi) \Rightarrow \Re(x \psi, p \psi)=0
$$

In the second case, the Schwarz inequality becomes an equality if and only if the terms $x \psi$ and $p \psi$ are linearly dependent, ie $p \psi=\lambda x \psi$.
From the first condition we get

$$
\begin{aligned}
\Re(x \psi, p \psi) & =(x \psi, p \psi)+(x \psi, p \psi)^{*} \\
& =(x \psi, p \psi)+(p \psi, x \psi) \Leftrightarrow \\
\Leftrightarrow 0 & =(\psi,(x p+p x) \psi) \\
& =\lambda(x \psi, x \psi)+\lambda^{*}(x \psi, x \psi) \Rightarrow \\
\Rightarrow 0 & =\lambda+\lambda^{*} \\
& =\Re(\lambda),
\end{aligned}
$$

ie, $\lambda=i \alpha$ for some real $\alpha$. We then have

$$
\begin{aligned}
p \psi(x) & =i \alpha x \psi(x) \Leftrightarrow \\
\Leftrightarrow-i \hbar \frac{\partial}{\partial x} \psi(x) & =i \alpha x \psi(x) \Leftrightarrow \\
\Leftrightarrow \frac{\partial}{\partial x} \psi(x) & =-\frac{\alpha}{\hbar} x \psi(x),
\end{aligned}
$$

which results in the Gaussian wave function

$$
\psi=A \exp \left(-\frac{\alpha x^{2}}{2 \hbar}\right)
$$

We set $\alpha>0$ so that the integral of $\psi^{*} \psi$ is finite.

## Exercise 9.2 Symmetry and projective representations - time translations

Time translations are represented by unitary operators $U(t)$.
a) Using the associativity of the matrix product,

$$
\begin{aligned}
{[U(x) U(y)] \quad U(z) } & =U(x) \quad[U(y) U(z)] \Leftrightarrow \\
\Leftrightarrow w(x, y) U(x+y) U(z) & =U(x) w(y, z) U(y+z) \Leftrightarrow \\
\Leftrightarrow w(x, y) w(x+y, z) U(x+y+z) & =w(y, z) w(x, y+z) U(x+y+z) \Rightarrow \\
\Rightarrow w(x, y) w(x+y, z) & =w(y, z) w(x, y+z)
\end{aligned}
$$

Setting $y=0$ we get

$$
\begin{aligned}
w(x, 0) w(x, z) & =w(0, z) w(x, z) \Rightarrow \\
\Rightarrow w(x, 0) & =w(0, z)
\end{aligned}
$$

b) We want $\tilde{w}\left(t_{1}, t_{2}\right)=1$.

$$
\begin{aligned}
\tilde{U}\left(t_{1}\right) \tilde{U}\left(t_{2}\right) & =\phi\left(t_{1}\right) U\left(t_{1}\right) \phi\left(t_{2}\right) U\left(t_{2}\right) \\
\tilde{w}\left(t_{1}, t_{2}\right) \tilde{U}\left(t_{1}+t_{2}\right) & =\phi\left(t_{1}\right) \phi\left(t_{2}\right) U\left(t_{1}\right) U\left(t_{2}\right) \\
\tilde{w}\left(t_{1}, t_{2}\right) \phi\left(t_{1}+t_{2}\right) U\left(t_{1}+t_{2}\right) & =\phi\left(t_{1}\right) \phi\left(t_{2}\right) w\left(t_{1}, t_{2}\right) U\left(t_{1}+t_{2}\right) \\
\tilde{w}\left(t_{1}, t_{2}\right) & =\frac{\phi\left(t_{1}\right) \phi\left(t_{2}\right)}{\phi\left(t_{1}+t_{2}\right)} w\left(t_{1}, t_{2}\right)=1
\end{aligned}
$$

c) To show that $w(t, 0)=1 \Rightarrow \phi(0)=1$ we do

$$
\begin{aligned}
w\left(t_{1}, t_{2}\right) & =\frac{\phi\left(t_{1}+t_{2}\right)}{\phi\left(t_{1}\right) \phi\left(t_{2}\right)} \\
w(t, 0) & =\frac{\phi(t+0)}{\phi(t) \phi(0)} \\
1 & =\frac{1}{\phi(0)}
\end{aligned}
$$

Let's now assume that $\phi(t)$ satisfies the condition given and test $\phi(t) e^{i \alpha t}$,

$$
\frac{\phi\left(t_{1}\right) e^{i \alpha t_{1}} \phi\left(t_{2}\right) e^{i \alpha t_{2}}}{\phi\left(t_{1}+t_{2}\right) e^{i \alpha\left(t_{1}+t_{2}\right)}} w\left(t_{1}, t_{2}\right)=\frac{\phi\left(t_{1}\right) \phi\left(t_{2}\right) e^{i \alpha\left(t_{1}+t_{2}\right)}}{\phi\left(t_{1}+t_{2}\right) e^{i \alpha\left(t_{1}+t_{2}\right)}} w\left(t_{1}, t_{2}\right)=\frac{\phi\left(t_{1}\right) \phi\left(t_{2}\right)}{\phi\left(t_{1}+t_{2}\right)} w\left(t_{1}, t_{2}\right)=1
$$

d) $w$ differentiable, $\phi^{\prime}(0)=0, \phi(0)=1$.

$$
\begin{aligned}
\left.\frac{\partial}{\partial y} w(x, y)\right|_{y=0} & =\left.\frac{\partial}{\partial y} \frac{\phi(x+y)}{\phi(x) \phi(y)}\right|_{y=0} \\
& =\left.\frac{1}{\phi(x)} \frac{\partial}{\partial y} \frac{\phi(x+y)}{\phi(y)}\right|_{y=0} \\
& =\left.\frac{1}{\phi(x)} \frac{\left[\frac{\partial}{\partial y} \phi(x+y)\right] \phi(y)-\left[\frac{\partial}{\partial y} \phi(y)\right] \phi(x+y)}{\phi(y)^{2}}\right|_{y=0} \\
& =\frac{1}{\phi(x)} \frac{\left[\frac{\partial}{\partial x} \phi(x)\right] 1-0 \phi(x+y)}{1^{2}} \\
& =\frac{\frac{\partial}{\partial x} \phi(x)}{\phi(x)}=\frac{\partial}{\partial x} \ln \phi(x)
\end{aligned}
$$

e) We will see that the system

$$
\left\{\begin{array}{l}
\left.\frac{\partial}{\partial y} w(x, y)\right|_{y=0}=\frac{\partial}{\partial x} \ln \phi(x) \\
\phi(0)=1
\end{array}\right.
$$

always has a solution when $w$ verifies the cocycle condition. We start by applying a derivative in order to $z$ to both sides of that equation, when $z=0$,

$$
\begin{aligned}
& w(x, y) w(x+y, z)=w(y, z) w(x, y+z) \\
&\left.\frac{\partial}{\partial z} w(x, y) w(x+y, z)\right|_{z=0}=\left.\frac{\partial}{\partial z} w(y, z) w(x, y+z)\right|_{z=0} \\
&\left.w(x, y) \frac{\partial}{\partial z} w(x+y, z)\right|_{z=0}=\left.w(y, 0) \frac{\partial}{\partial z} w(x, y+z)\right|_{z=0}+\left.w(x, y+0) \frac{\partial}{\partial z} w(y, z)\right|_{z=0} \\
& w(x, y) \frac{\partial}{\partial y} \ln \phi(x+y)=1 \frac{\partial}{\partial y} w(x, y)+w(x, y) \frac{\partial}{\partial y} \ln \phi(y) \\
& w(x, y)\left[\frac{\partial}{\partial y} \ln \phi(x+y)-\frac{\partial}{\partial y} \ln \phi(y)\right]=\frac{\partial}{\partial y} w(x, y) \\
& \frac{\partial}{\partial y}[\ln \phi(x+y)-\ln \phi(y)]=\frac{\partial}{\partial y} w(x, y) \\
& w(x, y) \\
& \frac{\partial}{\partial y} \ln \frac{\phi(x+y)}{\phi(y)}=\frac{\partial}{\partial y} \ln w(x, y) \\
& \frac{\partial}{\partial y} \ln \frac{\phi(x+y)}{\phi(x) \phi(y)}=\frac{\partial}{\partial y} \ln w(x, y)
\end{aligned}
$$

which recovers the result from d) at $y=0$.

## Exercise 9.3 Space translations in the plane

a) We have $A=i a P_{1}$ and $B=i b P_{2}$, which gives us the commutator

$$
[A, B]=\left[i a P_{1}, i b P_{2}\right]=(i a)(i b)\left[P_{1}, P_{2}\right]=(i a)(i b)(i \alpha \mathbb{1})=-i \alpha a b \mathbb{1}
$$

Since the commutator between these two operators is given by a constant times the identity, all commutators of higher order in the Baker-Campbell-Hausdorff formula vanish. For instance, $[A[A, B]]=-i \alpha a b[A, \mathbb{1}]=0$. We have therefore

$$
\begin{aligned}
e^{A} e^{B} & =\exp \left(A+B+\frac{1}{2}[A, B]+\frac{1}{12}[A,[A, B]]-\frac{1}{12}[B,[A, B]]+\ldots\right) \\
e^{i a P_{1}} e^{i b P_{2}} & =\exp \left(i a P_{1}+i b P_{2}+\frac{1}{2}(-i \alpha a b \mathbb{1})+\frac{1}{12} 0-\frac{1}{12} 0+0\right) \\
& =e^{i\left(a P_{1}+b P_{2}\right)} e^{\frac{-i \alpha a b}{2}} .
\end{aligned}
$$

b) In this more general case we have $A=i\left(a P_{1}+b P_{2}\right), B=i\left(a^{\prime} P_{1}+b^{\prime} P_{2}\right)$, and the commutator is given by

$$
\begin{aligned}
{[A, B] } & =\left[i\left(a P_{1}+b P_{2}\right), i\left(a^{\prime} P_{1}+b^{\prime} P_{2}\right)\right] \\
& =-a a^{\prime}\left[P_{1}, P_{1}\right]-a b^{\prime}\left[P_{1}, P_{2}\right]-b a^{\prime}\left[P_{2}, P_{1}\right]-b b^{\prime}\left[P_{2}, P_{2}\right] \\
& =i \alpha\left(a^{\prime} b-a b^{\prime}\right) \mathbb{1}
\end{aligned}
$$

Applying two translations consecutively we obtain

$$
\begin{aligned}
T(\vec{r}) T\left(\vec{r}^{\prime}\right) & =e^{i \vec{r} \cdot \vec{P}} e^{i \vec{r}^{\prime} \cdot \vec{P}} \\
& =e^{i\left(\vec{r}+\vec{r}^{\prime}\right) \cdot \vec{P}} e^{\frac{i \alpha\left(a^{\prime} b-a b^{\prime}\right)}{2}} \\
& =T\left(\vec{r}+\vec{r}^{\prime}\right) e^{\frac{-i \alpha \vec{r} \times \vec{r}^{\prime}}{2}},
\end{aligned}
$$

where we defined $\vec{r} \times \vec{r}^{\prime}=a b^{\prime}-a^{\prime} b$ (just the $z$ component of the vector product, with no direction assigned).
We would like to define a gauge transformation $\tilde{T}=e^{i \theta(\vec{r})} e^{i \vec{r} \cdot \vec{P}}$ such that $\tilde{T}\left(\vec{r}+\overrightarrow{r^{\prime}}\right)=\tilde{T}(\vec{r}) \tilde{T}\left(\overrightarrow{r^{\prime}}\right)$.
This would imply

$$
\begin{aligned}
e^{i \theta\left(\vec{r}+\vec{r}^{\prime}\right)} T\left(\vec{r}+\overrightarrow{r^{\prime}}\right) & =e^{i \theta(\vec{r})} T(\vec{r}) e^{i \theta\left(\vec{r}^{\prime}\right)}\left(\overrightarrow{r^{\prime}}\right) \\
e^{i \theta\left(\vec{r}+\vec{r}^{\prime}\right)} T\left(\vec{r}+\overrightarrow{r^{\prime}}\right) & =e^{i \theta(\vec{r})} e^{i \theta\left(\vec{r}^{\prime}\right)} T\left(\vec{r}+\vec{r}^{\prime}\right) e^{\frac{-i \alpha \vec{r}^{\prime} \times \vec{r}^{\prime}}{2}} \\
\theta\left(\vec{r}+\vec{r}^{\prime}\right) & =\theta(\vec{r})+\theta\left(\vec{r}^{\prime}\right)-\frac{\alpha}{2}\left(\vec{r} \times \vec{r}^{\prime}\right),
\end{aligned}
$$

but it is impossible to define a function of the sum of two vectors that takes into account the vector product between (for instance, the sum is commutative while the vector product is anticommutative).

## Exercise 9.4 Unitary and antiunitary symmetries

a unitary operator $U$ will act on the scalar product as $(U \phi, U \psi)=(\phi, \psi)$. On the other hand, an antiunitary operator $A$ will act as $(A \phi, A \psi)=(\phi, \psi)^{*}=(\psi, \phi)$.
a) In the exercise sheet, we have $T^{2}=1$ because we were considering our new favourite framework: dealing with bosons. I won't use that here, so I'd cut it from the exercise sheet. I'll check with JF this morning anyway.
The time evolution of a state of a system ruled by the Hamiltonian $H$ is given by

$$
\psi\left(t_{1}\right)=e^{-i\left(t_{1}-t_{0}\right) H / \hbar} \psi\left(t_{0}\right)
$$

. When the time interval $\delta t=t_{1}-t_{0}$ is very small we can write (for simplicity let's say $t_{0}=0$ and $\psi(0)=\psi)$

$$
\psi(\delta t)=\left(\mathbb{1}-\frac{i H}{\hbar} \delta t\right) \psi .
$$

The time reversal operator acts as

$$
T e^{-i H \delta t} \psi=e^{-i H(-\delta t)} \psi
$$

which for small $\delta t$ becomes

$$
\begin{aligned}
T\left(\mathbb{1}-\frac{i H}{\hbar} \delta t\right) \psi & =\left(\mathbb{1}-\frac{i H}{\hbar}(-\delta t)\right) T \psi, \quad \forall \psi \Rightarrow \\
\Rightarrow-\frac{i \delta t}{\hbar} H T \psi & =T \frac{i \delta t}{\hbar} H \psi, \quad \forall \psi \Rightarrow \\
\Rightarrow-i H T \psi & =T i H \psi, \quad \forall \psi
\end{aligned}
$$

## sol. 1

An useful characteristic of unitary and antiunitary operators that follows from the way they act on the inner product is how they act complex numbers,

$$
\begin{aligned}
U z=z U, & U \text { unitary; } \\
A z=z^{*} A, & A \text { antiunitary. }
\end{aligned}
$$

Suppose that $T$ were unitary. In that case we would have

$$
\begin{aligned}
& -i H T \psi=i T H \psi, \quad \forall \psi \Leftrightarrow \\
& \Leftrightarrow H T \psi=-T H \psi, \quad \forall \psi .
\end{aligned}
$$

Consider now $\psi_{n}$ to be an eigenstate of $H$ of energy $E_{n}$. The correspondent time-reversed state is $T \psi_{n}$, which would have energy

$$
H T \psi_{n}=-T H \psi_{n}=-E_{n} T \psi_{n}
$$

This would imply that the energy spectrum of a time-reversed system would be the symmetric of that of the original system. This does not make sense physically - the energy of the states should remain constant under time reversal. Consider for instance the case of a free particle. Its energy spectrum ranges from 0 to $+\infty$, and negative energies make no sense here (good old emotional argument)). If we want to say that a system presents time-reversal symmetry, then the spectrum of $H$ should remain constant under that transformation, which is achieved if $T$ is antiunitary,

$$
\begin{aligned}
-i H T \psi & =T i H \psi, \quad \forall \psi \Leftrightarrow \\
\Leftrightarrow-i H T \psi & =-i T H \psi, \quad \forall \psi \Leftrightarrow \\
\Leftrightarrow H T \psi & =T H \psi, \quad \forall \psi
\end{aligned}
$$

## OR sol. 2

We may also say we have $H T \psi=i T i H \psi$ and that one requirement for time symmetry is that the expectation value of $H$ is invariant under time reversal,

$$
\begin{aligned}
(\psi, H \psi) & =(T \psi, H T \psi) \\
& =(T \psi, i T i H \psi) \\
& =i(T \psi, T i H \psi) \\
& = \begin{cases}i(\psi, i H \psi), & T \text { unitary } \\
i(\psi, i H \psi) *, & T \text { antiunitary }\end{cases} \\
& = \begin{cases}-(\psi, H \psi), & T \text { unitary } \\
i[i(\psi, H \psi)]^{*}, & T \text { antiunitary }\end{cases} \\
& = \begin{cases}-(\psi, H \psi), & T \text { unitary } \\
i(-i)(H \psi, \psi), & T \text { antiunitary }\end{cases} \\
& = \begin{cases}-(\psi, H \psi), & T \text { unitary } \\
(\psi, H \psi), & T \text { antiunitary }\end{cases}
\end{aligned}
$$

so $T$ has to be antiunitary.
b) In the exercise sheet, $\vec{x}=(X, Y, Z)$ is the operator that measures the position.

The parity or space-inversion operator acts as

$$
P \vec{x} \psi=-\vec{x} P \psi
$$

A reasonable requirement for parity is that the expectation value of $\vec{x}$ of a space-inverted state must be symmetric to the one of the original state,

$$
\begin{aligned}
(P \psi, \vec{x} P \psi) & =-(\psi, \vec{x} \psi), \forall \psi \Leftrightarrow \\
\Leftrightarrow-(P \psi, P \vec{x} \psi) & =-(\psi, \vec{x} \psi),
\end{aligned}
$$

which implies that $P$ is unitary.

