Programming techniques for physical simulations Exercise 11

November 25, 2009

The aim of this week's exercise is to program a fast library for matrixmatrix multiplication of dense, real, dynamically-allocated matrices. As a first step, implement a simple version in the skeleton code provided. Once you have a correct implementation you add improvements while keeping the interface fixed. Some suggestions for improvements have been made in the lecture - you might want to exploit caching effects and vectorization, but of course we welcome any additional ideas you have! inline void set(double *A, double *B, const int n);

inline void mult(const double *A, const double *B, double *C, const int n);

```
int main(){
     const int n = 700;
     int n_iterations = 10;
     double *A = new double[n * n];
     double *B = new double[n * n];
double *C = new double[n * n];
     set(A, B, n);
    for (int i = 0; i < n_{ierations}; ++i) {
          mult(A, B, C, n);
     }
}
inline void set(double *A, double *B const int n)
{
    //implement!
}
inline void mult(const double *A, const double *B, double *C, const int n)
{
    //implement!
}
```